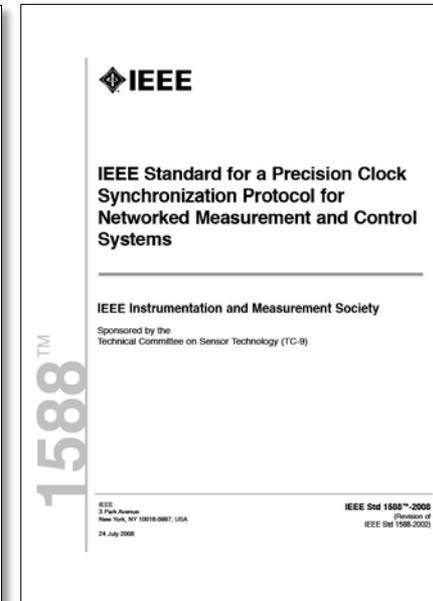


# Use of IEEE 1588–2008 for a Sampled Value Process Bus in Transmission Substations

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# Presentation Overview

- Transmission substations
- Substation automation systems & IEC 61850
- Process Bus timing requirements
- IEEE Std 1588 testing method
- IEEE Std 1588 performance results
- Recommendations

# Transmission Substations



# The “Transmission Smart Grid”

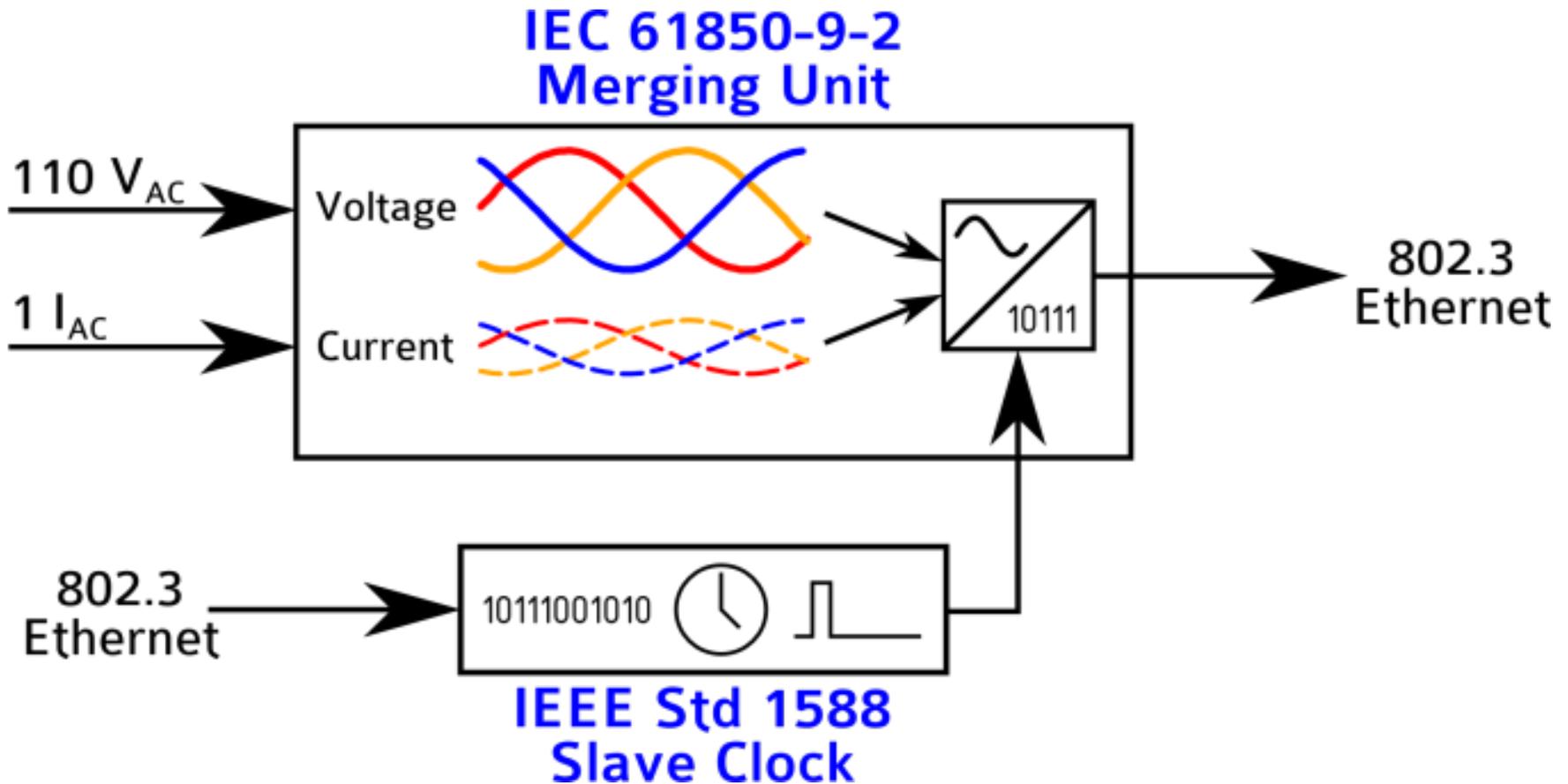
- IEC and NIST have released Smart Grid ‘roadmaps’.
  - ‘Foundation’ standards are recommended.
  - Cooperation between the organisations.
- Characteristics
  - Digitisation
  - Autonomy
  - Coordination
  - Self healing
- Benefits
  - Reliability
  - Flexibility
  - New Technology



# Process Bus Definition

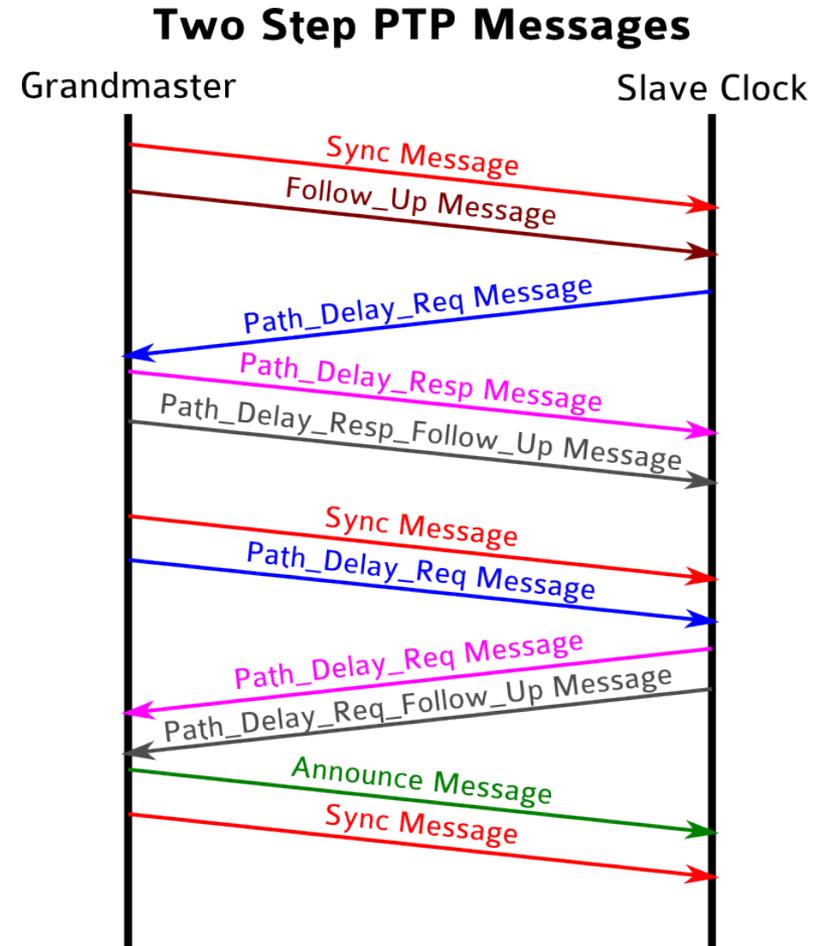
- The process bus carries information from Primary Plant to the SAS, and from the SAS to the primary plant.
- Requires time synchronisation.
- The “merging unit” digitises voltage, current and digital inputs and creates data stream.

# Merging Unit Sampling



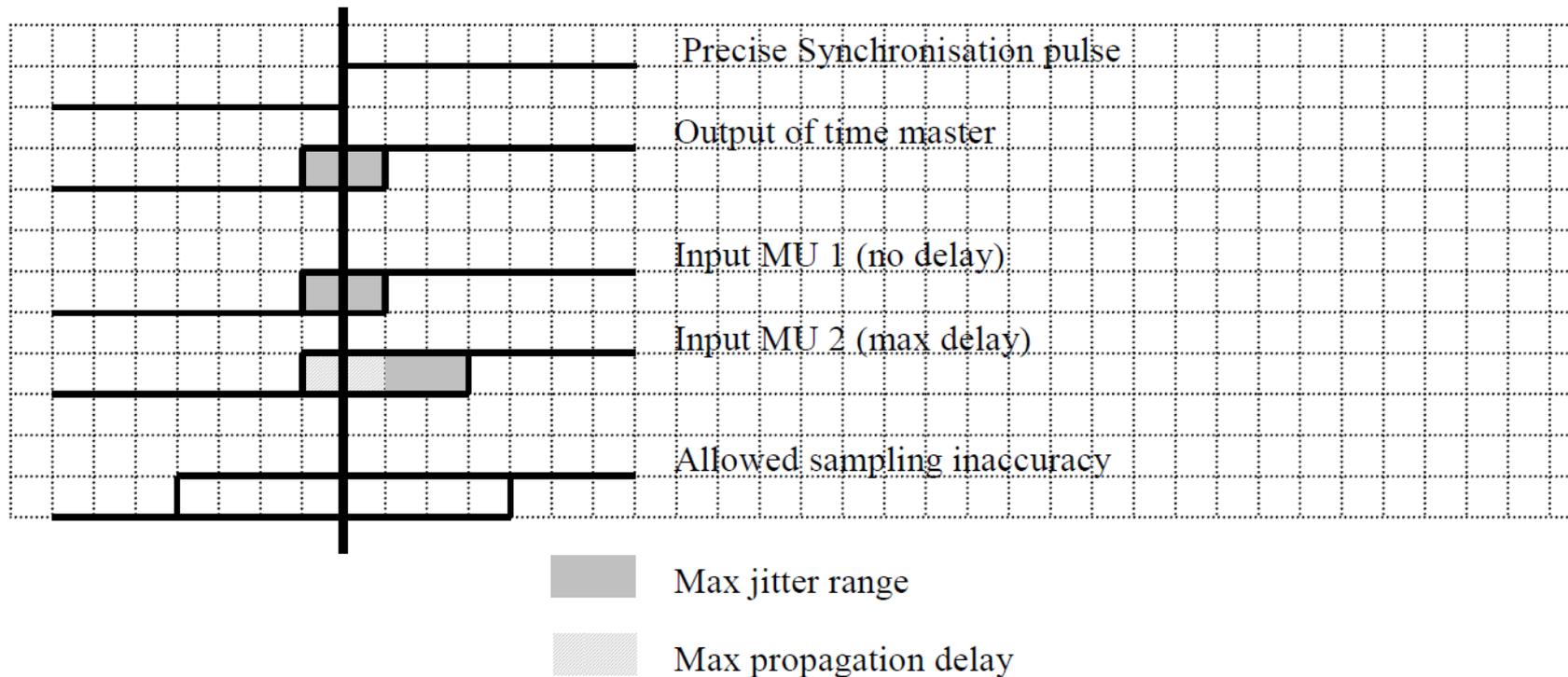
# IEEE Std 1588–2008 / PTPv2

- **Grandmaster** provides reference.
- **Slave clock** uses time info, e.g. to create 1PPS signal.
- Ethernet based timing standard.
- Time recovery through message passing.

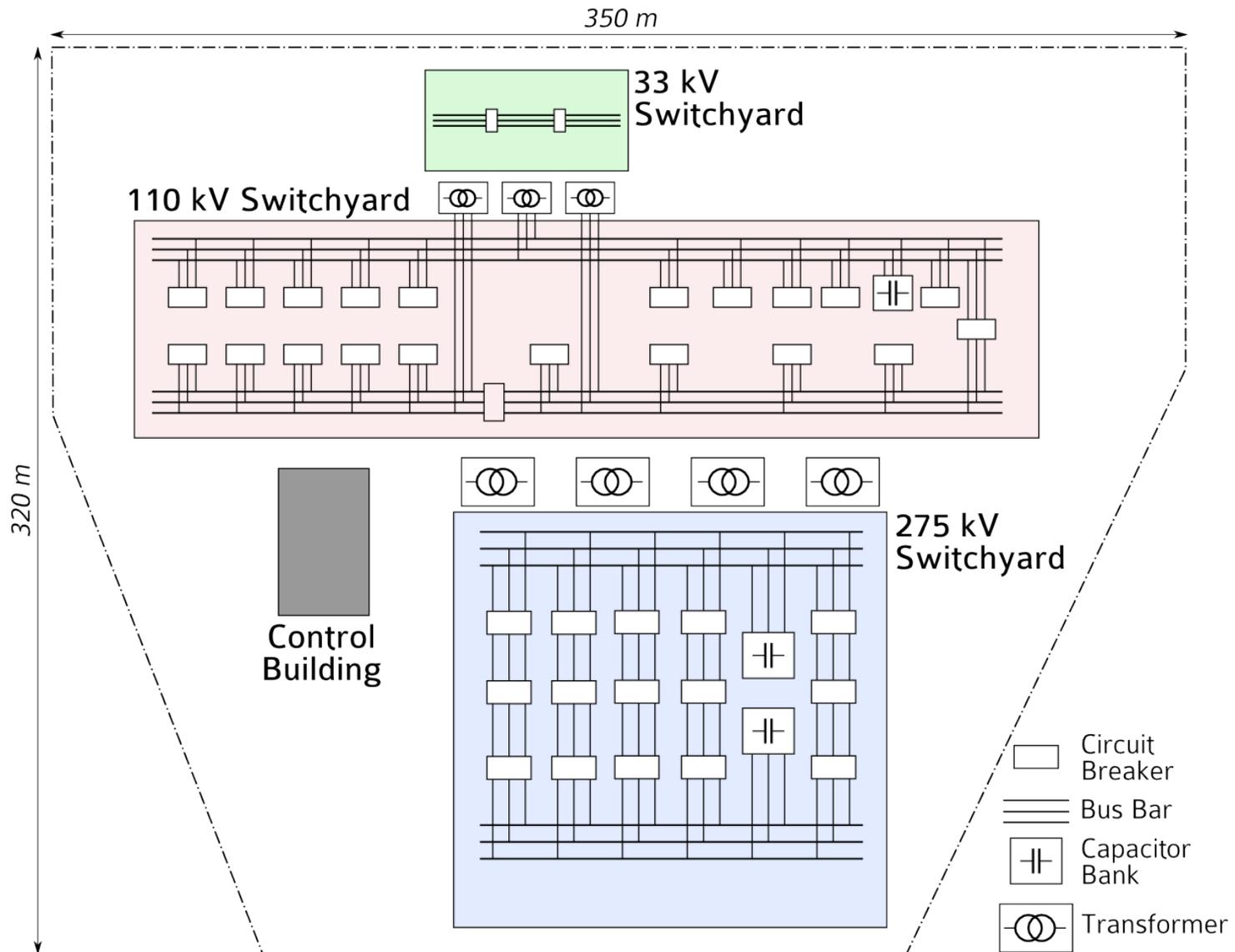


# Performance Requirement for Timing

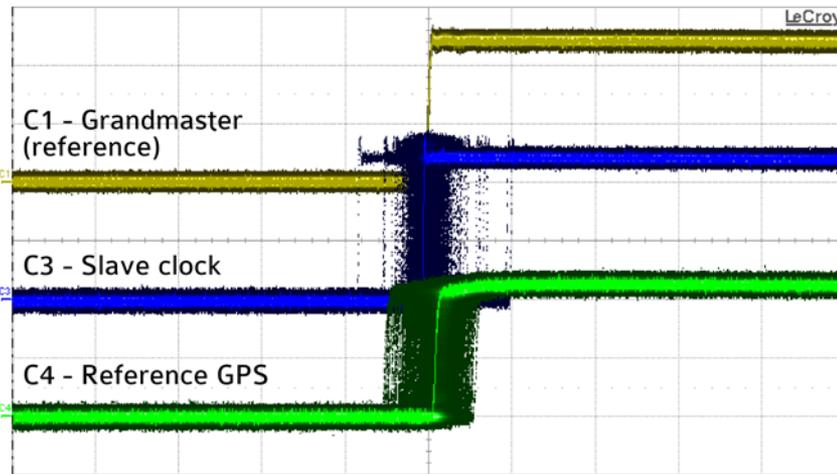
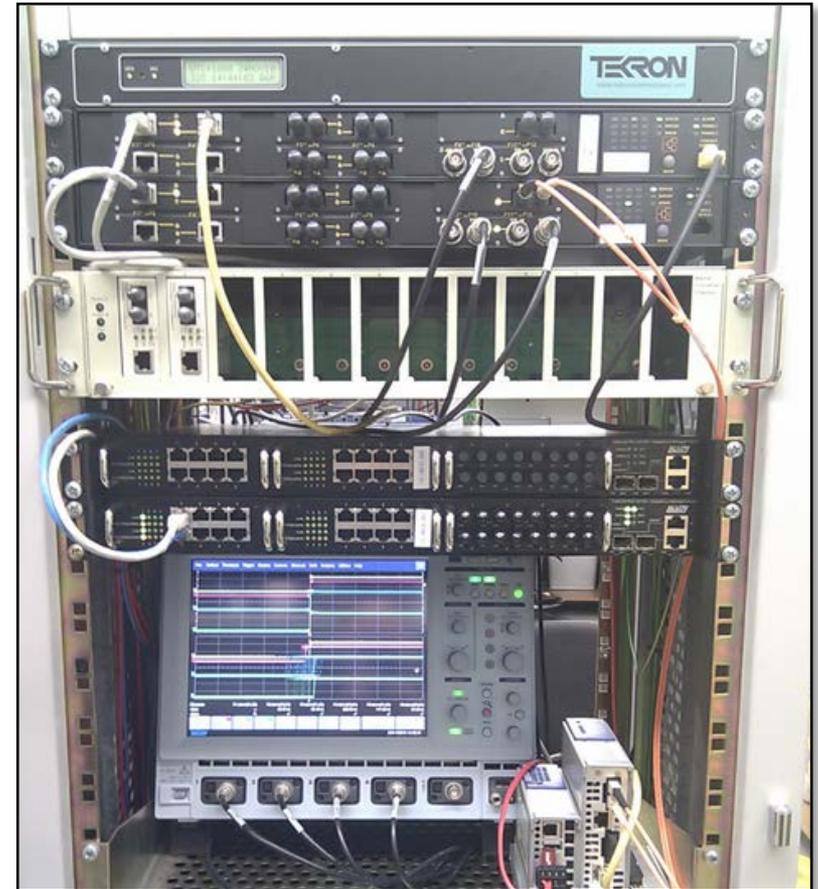
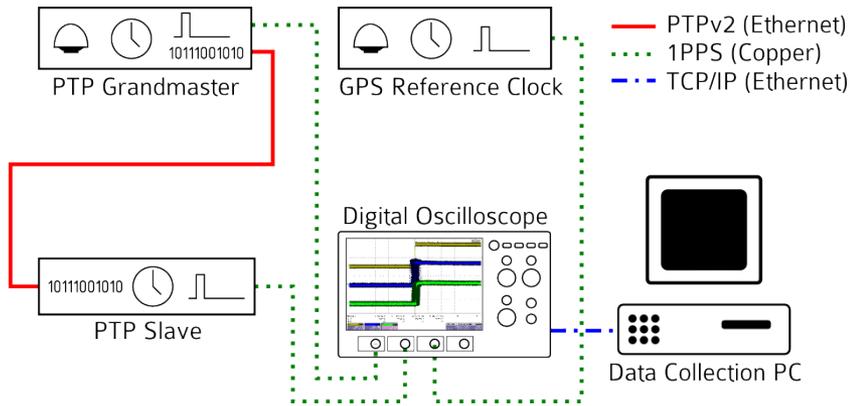
- $\pm 1 \mu\text{s}$  for sync pulse to achieve overall IEC 61850-5 class T4 ( $\pm 4 \mu\text{s}$ )



# Queensland Substation Layout



# Test Equipment



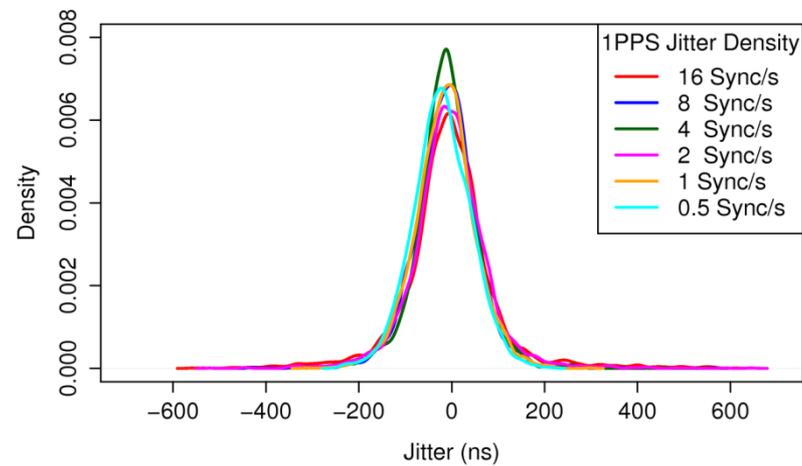
# Tests

- Steady state performance
  - Directly connected
  - Using transparent clocks
- Power on performance
- Loss of grandmaster/slave communications
- Loss of grandmaster external synchronisation

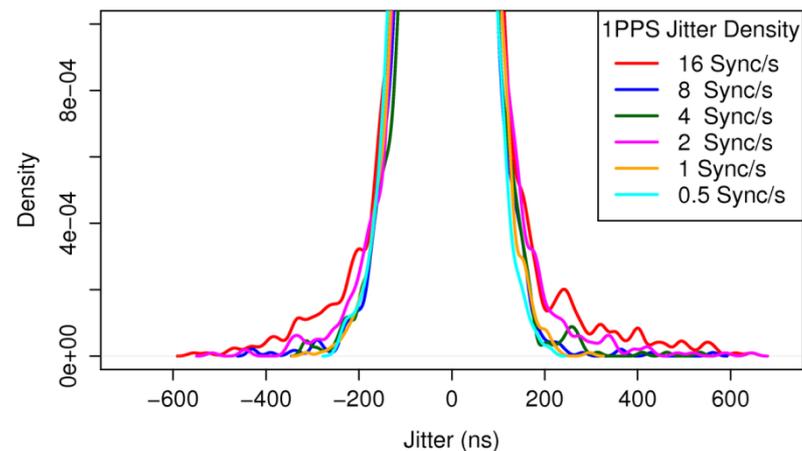
# Steady State Performance

- PTP parameters affect performance.
- IEEE Std PC37.238 Power Profile used.
- Peer-peer delay requests and announce messages fixed.
- Sync rate varied.

Effect of Sync Rate on Jitter

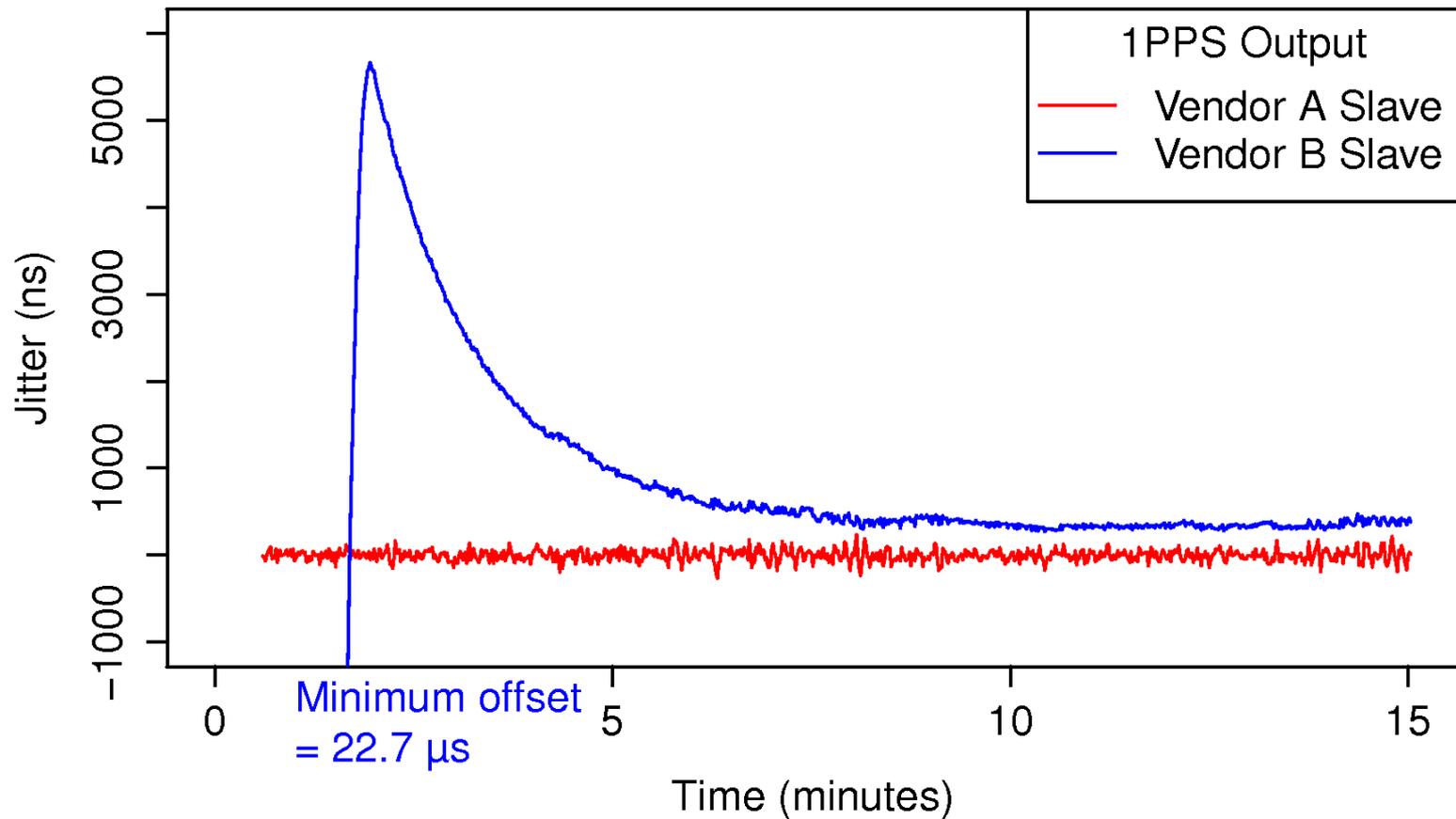


Effect of Sync Rate on Jitter



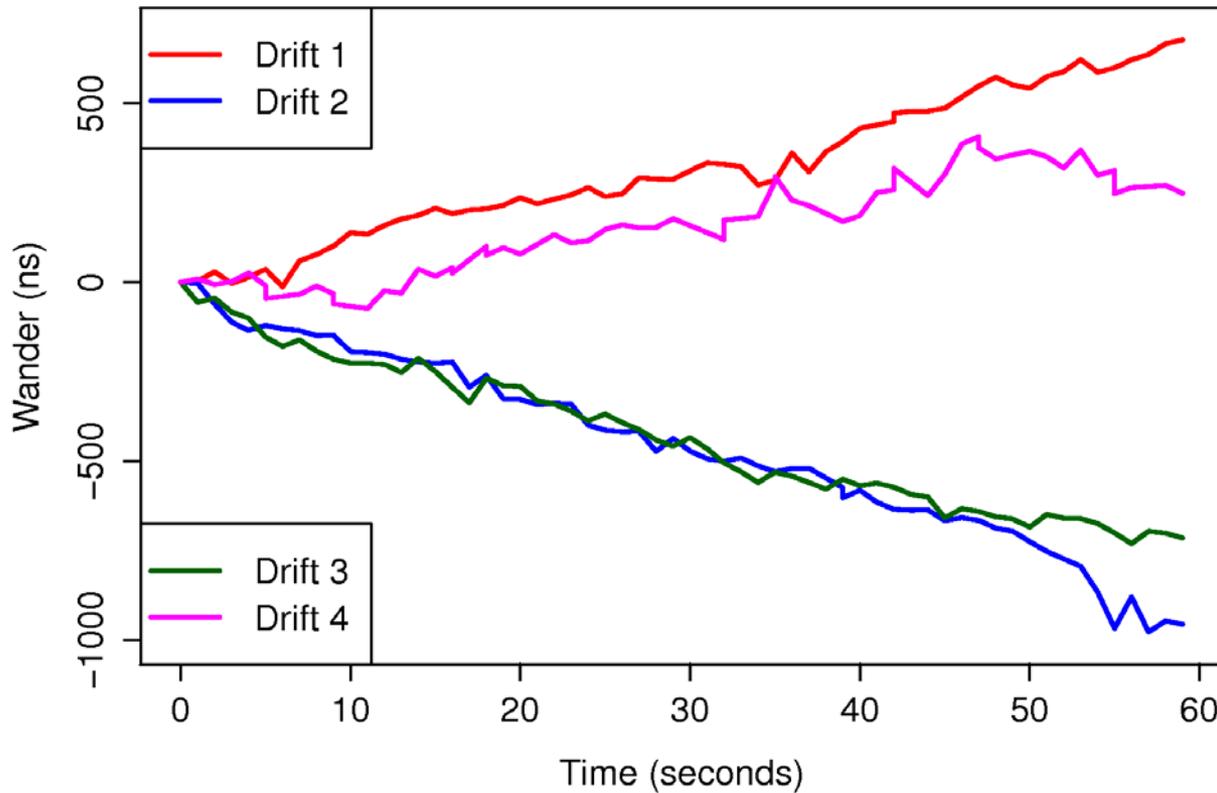
# 'Power On' Performance

## Slave Power-up Acquisition

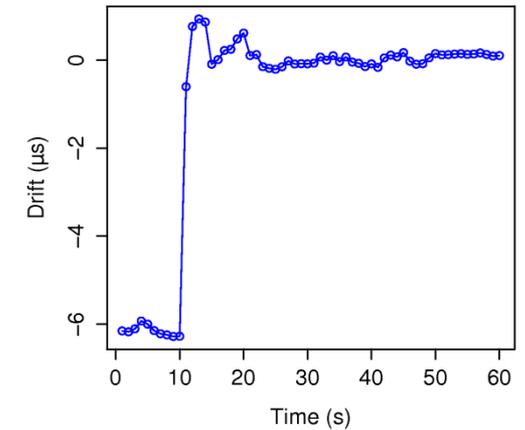


# Loss of Grandmaster/Slave Comms

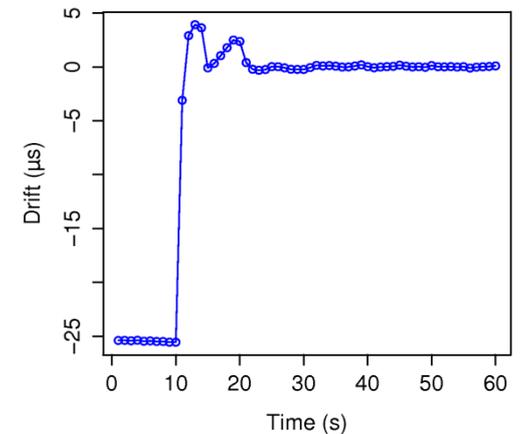
## PTP Slave Wander



## Slave Recovery From 6 $\mu$ s

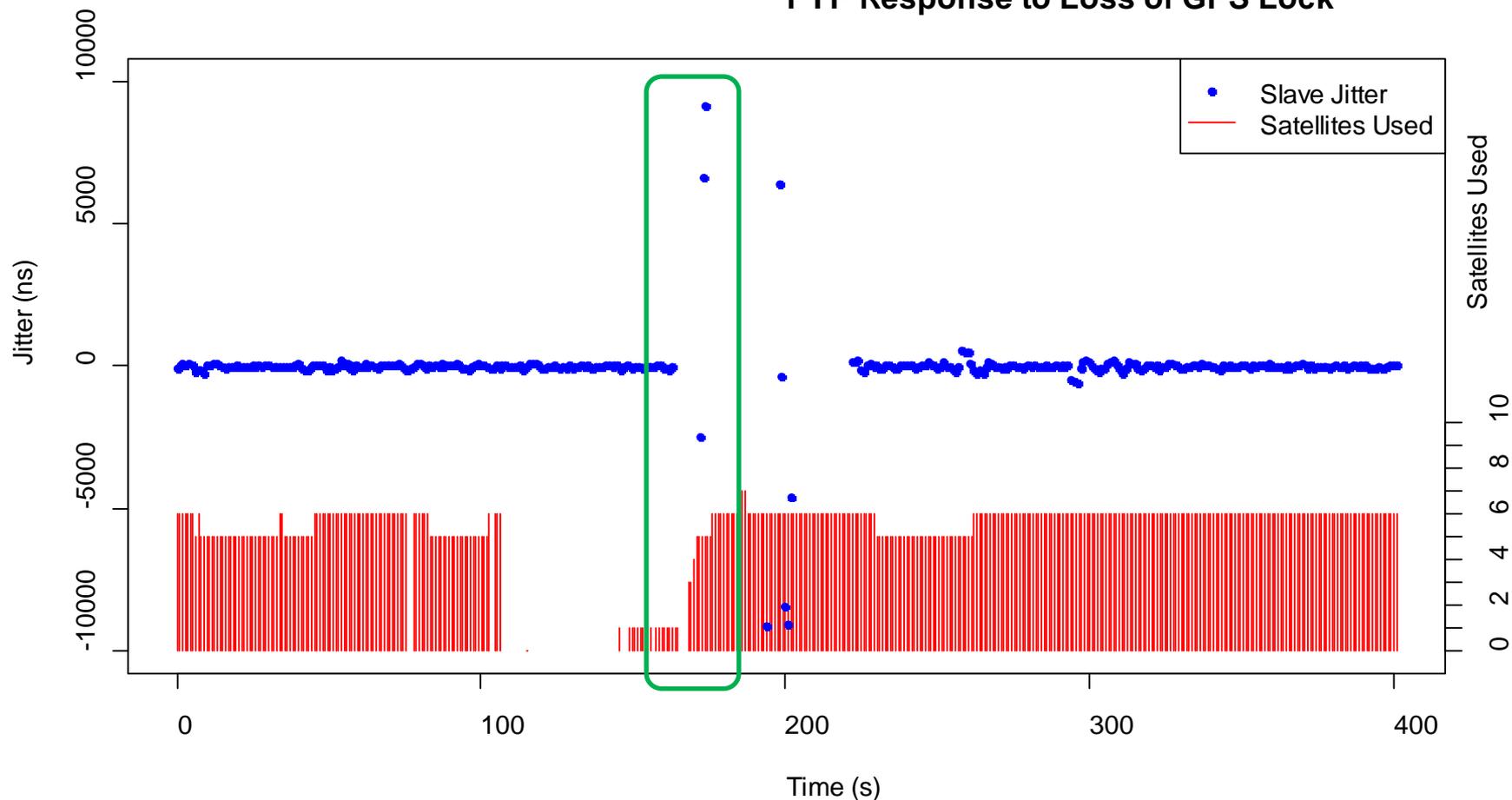


## Slave Recovery From 25 $\mu$ s



# Loss of Grandmaster Discipline Source

## PTP Response to Loss of GPS Lock

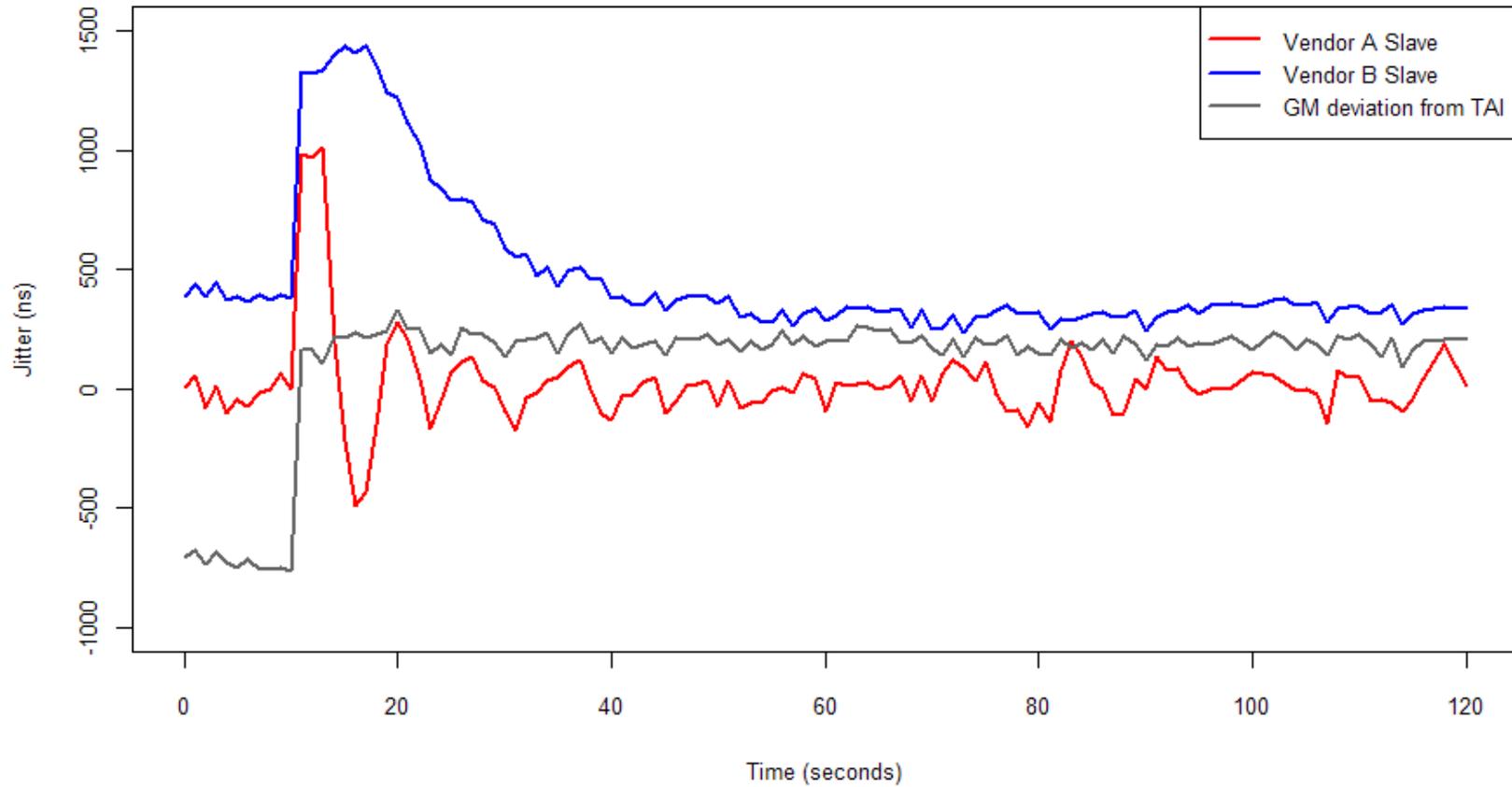


# Poor GPS Antenna Placement



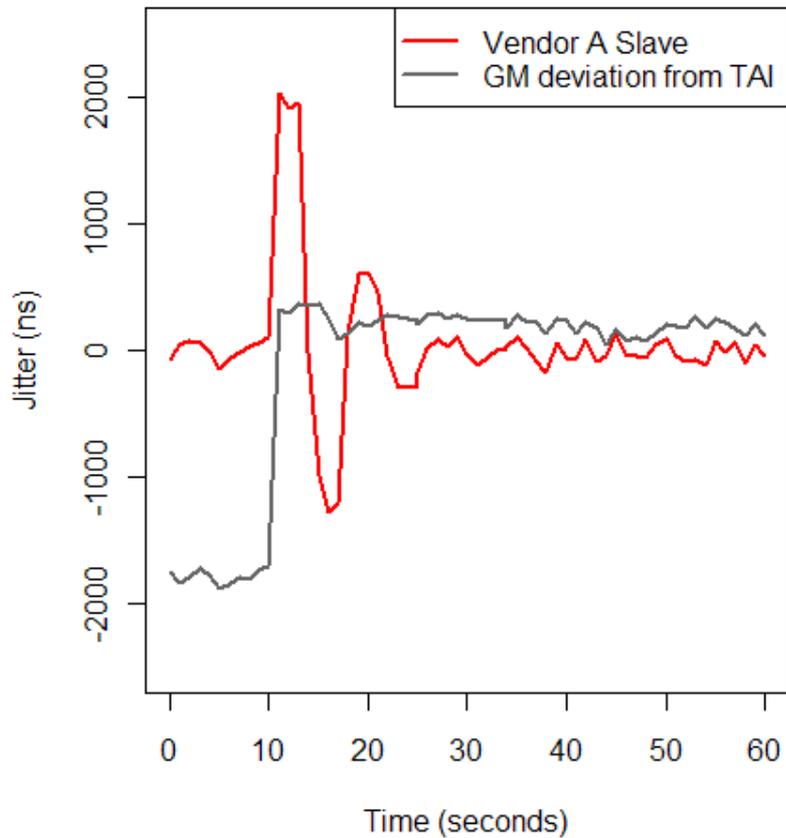
# Recreate Loss of GPS Fault

TAI Recovery – 964 ns step  
1 Sync Msg/sec

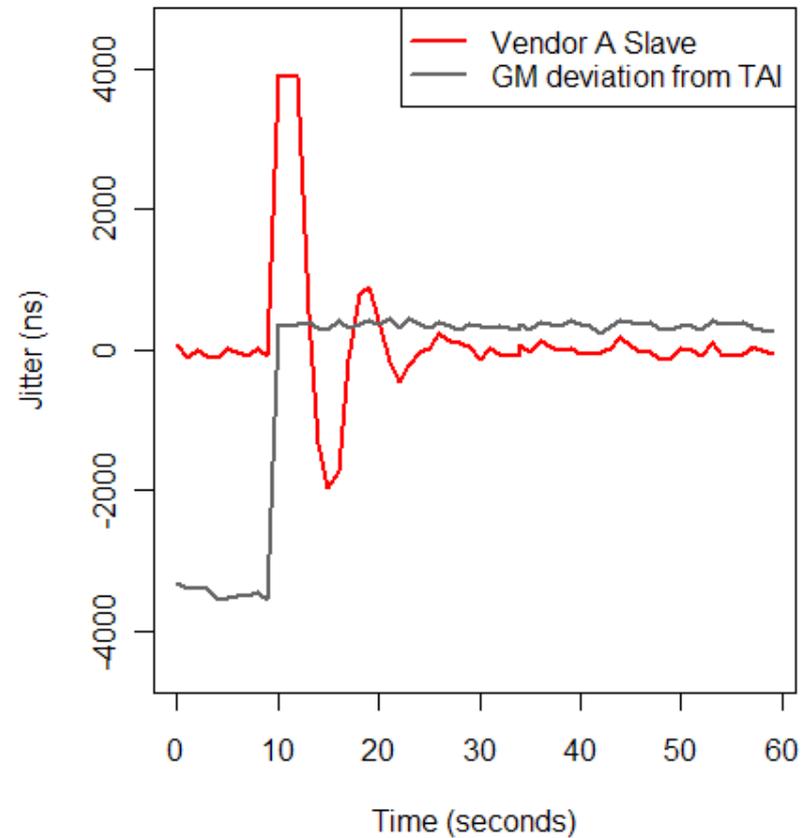


# Larger Error Recovery

TAI Recovery – 1919 ns step  
1 Sync Msg/sec



TAI Recovery – 3890 ns step  
1 Sync Msg/sec



# Proposed Remedy

- Two alternatives:
  - Slower slew rate for slaves
  - Reduced wander in grandmaster.
- Slow slew rate:
  - Leads to errors between sites
  - Difficult to get consistency between vendors
- Reduced wander:
  - More expensive grandmaster required.
  - Improved performance overall

# Grandmaster Oscillators

- Invest in the best grandmaster available.
- Reduced phase noise will reduce system jitter too.
- Invest in grandmaster rather than slaves.

Oscillator Type	Stability
Crystal Oscillator (XO)	$10^{-4}$ to $10^{-5}$
Temperature Compensated Crystal Oscillator (TCXO)	$10^{-6}$
Oven Controlled Crystal Oscillator (OCXO)	$10^{-8}$ to $10^{-10}$
Rubidium Atomic Frequency Standard (Rb)	$10^{-10}$ to $10^{-11}$

Information from Bloch *et. al*, "Mass-Produced Quartz Oscillators as Low-Cost Replacement of Passive Rubidium Vapor Frequency Standards", 2007 IEEE International Frequency Control Symposium Jointly with the 21<sup>st</sup> European Frequency and Time Forum, Geneva, Switzerland.

# Conclusions

- PTPv2 meets timing requirements for process bus applications.
- Low cost clocks give jitter under  $\pm 300$  ns.
- Wander of grandmaster needs to be minimised.
- Transient response of slaves to corrections is a concern, and needs to be allowed for.
- IEEE Std 1588 and the IEC 61850 series facilitate the implementation of the transmission smart grid.